PGI Series Electric Parallel Gripper

PGI-140-80

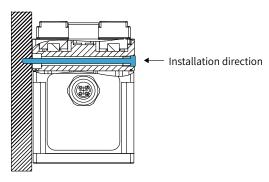


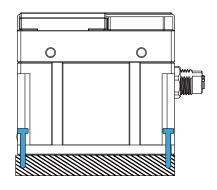
Based on the industrial requirements of 'long stroke, high load, and high protection level', DH-Robotics independently developed the PGI series of industrial electric parallel gripper. The PGI series is widely used in various industrial scenarios with positive feedback.



Installation

- 1. Front and rear installation: use front and rear screw holes for installation
- 2. Bottom installation: use bottom screw holes for installation





Product Features

Long Stroke

Long stroke reach to 80 mm. With the customization fingertips, it can stably grasp the medium and large objects below 3kg and suitable for lots of industrial scenes.

High Protection Level

The protection level of PGI-140-80 reaches to IP54, which is able to work under harsh environment with dust and liquid splash.

High Load

The maximum single-sided gripping force of PGI-140-80 is 140 N, and the maximum recommended load is 3 kg, which can meet more diverse gripping needs.

Application

In industrial scenarios, it is used for gripping, handling and assembly of heavy workpieces. Mostly used in new energy, auto parts, machining, 3C electronics and other industries.



Parameters

PGI-140-80

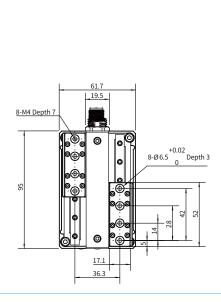
Product Parameter						
Grippir	ng force (pe	r jaw)	40~140 N			
Stroke				80 mm		
Recom	mended wo	orkpiece we	eight *	3 kg		
Openir	ng/Closing t	ime	0.7 s/0.7 s			
Repeat	accuracy (¡	oosition)	\pm 0.03 mm			
Noise emission			< 50 dB			
Weight			1 kg (exclude fingers)			
Driving	Oriving method Precise pla			lanetary gears + Rack and pinion		
Size			95 mm x 67.1 mm x 86 mm			
Working Environment						
Communication interface Standard: Modbus RTU Optional: TCP/IP, USB2.0, CAN2.0A, P						
Rated	voltage		24 V DC \pm 10%			
Rated o	current		0.5 A			
Peak current			1.2 A			
IP class IP 54					IP 54	
Recommended environment 0~40°C, under 85% RH						
Certific	cation		CE, FCC, RoHS			
Build-in Controller	Gripping Force Adjustable	Position Adjustable	Speed Adjustable	Drop Detection	Self-locking Mechanism	

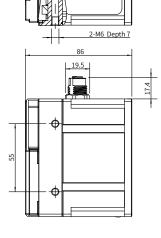


vertical Maximum	Force			
Fz:	300 N			
Allowable Moment				
Mx:	7 N⋅m			
My:	7 N⋅m			
Mz:	7 N⋅m			

^{&#}x27;It depends on the shape of the grasping object, the material and friction of the contact surface, and the acceleration of the motion, if you have any questions, please contact us.

Technical Drawings





2-Ø9 Depth 5.3 Ø5.5 Depth 49.4

